# **LogiCORE IP DUC/DDC Compiler v2.0**

DS766 October 16, 2012 **Product Specification**

**EXALINX** 

### **Introduction**

The Xilinx® LogiCORE™ IP DUC/DDC Compiler implements high-performance, optimized Digital Upand Down-Converter modules for use in wireless base stations and other suitable applications. In addition to a wide range of parameter options, resource trade-off options are available to tailor the core to a particular application.

### **Features**

- Generates Digital Up-Converter modules for a range of output sample rates between 30.76 and 245.76 MHz
- Generates Digital Down-Converter modules for a range of input sample rates between 30.76 and 184.32 MHz
- Supports LTE (1.4, 3, 5, 10, 15 and 20 MHz channels), TD-SCDMA (1.6 MHz channel) and W-CDMA (5 MHz channel)
- Supports up to 30 carriers (maximum dependent upon wireless standard and channel bandwidth)
- Implementation options to configure clock rate, enable optional control signals, and set resource usage preferences
- Supports  $F_s/4$  IF down-mixing in DDC configuration
- Supports programmable carrier frequencies (within the limits imposed by wireless standard)
- Supports fixed carrier phase offsets between 0 and 2 π
- Supports selectable carrier relative gain levels
- Data interfaces compliant with AXI4-Stream standard, allowing simple integration into signal processing data flows
- Easy-to-use programming interface compliant with AMBA® 3 APB specification
- Graphical User Interface (GUI) features: resource and latency estimation, frequency and phase raster reporting
- For use with Xilinx CORE Generator™ tool v14.3 and Vivado™ Design Suite 2012.3.



- <span id="page-0-1"></span>1. For a complete listing of supported devices, see the [release](http://www.xilinx.com/support/documentation/ip_documentation/xtp025.pdf)  [notes](http://www.xilinx.com/support/documentation/ip_documentation/xtp025.pdf) for this core.
- <span id="page-0-6"></span>2. Supported in ISE Design Suite implementations only.<br>3. Besources listed here are for Virtex-6 devices. For m
- <span id="page-0-2"></span>Resources listed here are for Virtex-6 devices. For more complete device performance numbers, see [Table 15](#page-33-0) to [Table 17](#page-35-0).
- <span id="page-0-3"></span>4. Based on 18K block RAMs
- <span id="page-0-4"></span>5. Performance numbers listed are for Virtex-6 FPGAs. For more complete performance data, see Performance and Resource<br>Utilization
- <span id="page-0-0"></span>6. For the supported version of the tools, see the Xilinx Design [Tools: Release Notes Guide](http://www.xilinx.com/support/documentation/sw_manuals/xilinx14_3/irn.pdf).
- <span id="page-0-5"></span>7. Supports only 7 series devices.

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# **Overview**

Digital Up-/Down-Converters (DUCs/DDCs) are key components in wireless communications systems, linking the baseband processing function with the radio front end.

A DUC forms part of the transmit path of digital radio front end (DFE) signal processing systems, and performs the function of filtering and up-converting the baseband signal to a higher sample rate to be passed to the radio front end via the Digital-to-Analog Converter (DAC), or to provide input to Crest Factor Reduction (CFR), Digital Pre-Distortion (DPD), I/Q offset correction, or other ancillary RF signal processing functions applied prior to the DAC. A DUC can include a multi-carrier mixing stage to combine multiple carriers into a composite passband signal.

A Digital Down-Converter (DDC) forms part of the receive path of a digital radio front-end signal processing system, following the Analog-to-Digital Converter (ADC), and Automatic Gain Control (AGC) or other ancillary RF signal processing functions. A DDC performs the function of filtering and down-converting the input RF sample rate to the baseband processing sample rate of the system (or an integer multiple thereof, for example 2x for symbol timing recovery.) The DDC can also perform frequency translation to shift each carrier of a multi-carrier system to baseband ready for de-modulation.

Channel selection filtering is normally incorporated into the filtering functions of DUC or DDC modules, and the sample rate conversion is normally performed most efficiently over multiple stages, with appropriate low-pass filtering for anti-aliasing or image rejection. The general architecture of a DUC or DDC therefore consists of multiple stages of filters and mixers, with the mixers being constructed variously from direct digital synthesizers, multipliers, and simple logic functions. This generalized architecture is illustrated in [Figure 1](#page-1-0) and [Figure 2.](#page-1-1)

<span id="page-1-1"></span><span id="page-1-0"></span>

*Figure 2:* **Generalized DDC Architecture**

Each core configuration has been designed to meet the requirements of the relevant air standard with a target spectral mask margin of approximately 5 to10 dB. The generated core meets or exceeds the EVM, ACLR and Blocking/ACS requirements for the relevant specifications, and EVM is further limited to 1.6% or less (standard/bandwidth dependent) to provide maximum flexibility in other areas of the wireless digital front end (DFE).

The DUC/DDC Compiler core provides an easy-to-use programming interface to allow carrier positions and relative gain levels to be programmed, as well as to provide configuration information and status reporting.

The DUC offers the capability to mix multiple carriers into a complex composite signal centered around zero Hz, while the DDC configuration offers the option of additionally translating a real passband composite signal centered at  $F_s/4$  Hz, where  $F_s$  is the input sample rate (usually the ADC sample rate), to a complex composite signal at zero Hz. This two-stage mixing process is illustrated in [Figure 3.](#page-2-0)

The core covers a wide range of parameter options, and automatically compiles a highly optimized filter cascade and mixer structure from the system-level specification. Advanced algorithms select appropriate mixing sample rates, filter types, datapath configurations, and other meta-parameters to create an efficient design that meets the performance requirements of the relevant wireless air interface specification and achieves the resource usage goals of the user.

The DUC/DDC Compiler core provides an easy-to-use programming interface to allow carrier positions and relative gain levels to be programmed, as well as providing a status reporting mechanism. This interface complies with the AMBA 3 APB bus specification.

<span id="page-2-0"></span>

# **I/O Port Definitions**

[Table 1](#page-3-0) defines the core port names and port functional descriptions.

### <span id="page-3-0"></span>*Table 1:* **Core Signal Pinout**



### *Table 1:* **Core Signal Pinout** *(Cont'd)*

<span id="page-4-1"></span><span id="page-4-0"></span>

*Table 1:* **Core Signal Pinout** *(Cont'd)*

<b>Name</b>	Interface	<b>Direction</b>	<b>Description</b>
INT LOSTOUTPUT	Interrupt	Output	Interrupt flag indicating that a lost output sample condition has been detected. Valid output was not accepted on the data output interface in one of the required clock cycles. The following sample was dropped to maintain the output sample rate. When asserted, this interrupt signal remains High until the interrupt is cleared or disabled using the programming interface, or ARESETN is asserted.
INT DUCDDC	Interrupt	Output	Combined interrupt output. This signal is the logical OR of all other interrupt output signals. It indicates that one or more interrupts are active.

# **Graphical User Interface**

The DUC/DDC Compiler core GUI has several pages with fields in which to set parameter values for the particular configuration required, while also providing some user feedback for information about the implementation. This section provides a description of each GUI field.

*Note:* The descriptions and screen captures are taken directly from the ISE Core Generator GUI - the same fields appear in the Vivado IP Catalog and usage is identical, although the look and feel might vary slightly.

<span id="page-5-0"></span>

*Figure 4:* **GUI Page 1, with IP Symbol Tab**

### **Tab 1: IP Symbol**

The IP Symbol tab illustrates the core pinout.

### **Tab 2: Implementation**

The Implementation tab displays:

- Resource estimation information
- Quantization and scaling details
- Estimated core latency in both clock cycles and time based on the specified clock rate

The estimated number of DSP slices is displayed in addition to an approximate count of the number of block RAM elements required to implement the design. Usage of general slice logic is not currently estimated. The results in the Resource Estimation are estimates only using equations that model the expected core implementation structure. Users should implement the core following generation for a more accurate report on resource usage. The final resource cost when integrated into the user application system might differ due to additional routing congestion. It is not guaranteed that the resource estimates provided in the GUI match the results of a mapped core implementation.

The latency report box provides an indication of the approximate expected delay of the core from input to output, in terms of both clock cycles and absolute time. This information is a useful metric for the core in assessing suitability for particular applications. The figure is approximate and users are encouraged to confirm the actual latency in simulation following core generation.

The Data Format box provides information on the quantization and scaling used by the core. Core inputs are assumed to range between -1.0 to +0.999.., that is, 1 integer bit with the remaining bits being fractional. Core outputs are scaled by the integer bit growth through the core. The Data Format information is provided to allow the user to decide how to handle the output samples. For example, the user might decide to saturate and round the sample values at the core output based on the reduced fractional width, removing some or all of the additional integer bits.

### **Tab 3: C Model**

This tab provides details on how to obtain a copy of the bit accurate C model for this core.

### **Page 1**

Page 1 of the GUI is shown in [Figure 4](#page-5-0).

- **Component Name:** The name of the core component to be instantiated. The name must begin with a letter and be composed of the following characters: a to z, 0 to 9, and "\_".
- **Core Type:** Select between DUC and DDC options.
- **Wireless Standard:** Select the required wireless air interface standard, LTE, TD-SCDMA or W-CDMA.
- **Channel Bandwidth:** Select between 1.4, 3, 5, 10, 15 and 20 MHz channel bandwidth options for LTE. This field is set automatically to 1.6 MHz for TD-SCDMA and to 5 MHz for W-CDMA.
- **Baseband Sample Rate:** The baseband sample rate value is selected automatically based on the Channel Bandwidth setting. The relevant values are: 1.28 or 2.56 MSPS for TD-SCDMA 1.6 MHz channel (normal or over-sampled); 3.84 or 7.68 MSPS for W-CDMA 5 MHz channel (normal or over-sampled); 1.92, 3.84, 7.68, 15.36, 23.04, 30.72 MSPS for LTE 1.4, 3, 5, 10, 15, 20 MHz channels respectively.
- **RF Sample Rate:** Select the RF sample rate value to suit the data converter sample rates in the application system, or to match up with another intermediate sample rate. For DUC implementation, the allowable RF

sample rate values are: 30.76, 61.44, 76.80, 92.16, 122.88, 153.60, 184.32, and 245.76 MSPS; while for DDCs, the range is: 30.76, 61.44, 76.80, 92.16, 122.88, 153.60, and 184.32 MSPS.

- **Digital IF:** Select the intermediate frequency mixing option to implement, either zero IF or  $F_s/4$ . Only available for DDC configurations. The  $F_s/4$  option adds an efficient quarter sample rate frequency translation stage to convert the RF input signal from a real passband signal centered at  $F_s/4$ , where  $F_s$  is the RF Sample Rate value, to a complex passband signal centered at 0 Hz, ready for extraction of individual carrier sample streams from the composite multi-carrier signal.
- **Number of Carriers:** Select the required number of carriers. Support for carrier options is dependent upon the Wireless Standard and Channel Bandwidth already selected. [Table 2](#page-7-0) shows the carrier options that are supported in the core. Some RF Sample Rate values reduce the number of carriers supported.



#### <span id="page-7-0"></span>*Table 2:* **Carrier Support Options**

- **IF Passband:** Select the required IF passband width in which you wish to place the carriers. The range of valid values for this option is: 5, 10, 15, 20, 30, 40, 50, 60, 80 and 100 MHz; however, some limits are applied to limit this range further. The minimum value is the smallest option in which all carriers fit, while the largest option is no more than twice than the minimum, or half of the RF Sample Rate value, whichever is smaller.
- **Number of Antennas:** Select the number of antennas to be implemented, up to 8 antennas in total. A separate datapath and rate conversion filter cascade are implemented for each antenna, and appropriate I/O pins appear on the IP symbol and in the output netlist for these datapaths.

## **Page 2**

[Figure 5](#page-8-0) shows the GUI when a single carrier is used.

<span id="page-8-0"></span>

*Figure 5:* **GUI Page 2, with Implementation Tab**

- **Clock Frequency:** The Clock Frequency is selected via a drop-down list which is limited to integer multiples of the RF Sample Rate, within the limits of the selected FPGA family and the selected speed grade.
- **Data Precision Input Data Width:** Select the required input data width, from 11 to 17 bits.
- **Data Precision Output Data Width:** Select the required output data width, from 11 to 18 bits.
- **Data Interface Format:** Select the interface format used for both input and output data ports, either separate I & Q data ports or a single complex data port with I & Q supplied in a TDM format (In-Phase first.) This option is only available if the clock frequency is at least twice the RF Sample Rate value; if it is less than twice the RF Sample Rate, it is set to separate I & Q data ports. The option is also disabled when using a DDC with the digital IF set as  $F_s/4$ , in which case only a real valued data signal is provided as input, and the output is separate I  $\&$  Q data ports.
- **Optional Pins Reset:** Select whether or not to add reset capability to the core. This option adds two reset pins to the core, one for the main datapath logic (ARESETN, active-Low) and another for the programming port (SREG\_PRESETn, active-Low.) ARESETN does not reset filter sample history.
- **Optimize Options Implementation Goal**: Select either Minimum Area or Maximum Speed as an Implementation Goal. The recommendation for this setting is to use Minimum Area first, as generally this setting also achieves maximum performance and does not require any additional resources; however, if timing

goals are not being achieved, the architectural changes enabled by the Maximum Speed setting can improve results, at the expense of an increase in core resource usage.

• **BRAM Usage**: Select whether to use more block RAMs or leave the decision to the filter sub-core functions to select storage type appropriately. This optimization directive is a goal and does not remove all block RAM usage from the core.

### <span id="page-9-1"></span>**Pages 3 & 4**

When multiple carriers are used, Page 3 ([Figure 6\)](#page-9-0) allows the specification of carrier frequencies and phase offsets for each carrier. Where more than 18 carriers are used (TD-SCDMA only), the carrier specification section runs onto Page 4 ([Figure 7\)](#page-10-0).

<span id="page-9-0"></span>

*Note:* Pages 3 & 4 are not present when a single carrier configuration is used.

*Figure 6:* **GUI Page 3, with C Model Tab**

<span id="page-10-0"></span>

		DUC/DDC Compiler				$\sim$ $\vert$ $\Box$
Documents View						
we construct the control of $\mathsf{C}\,\mathsf{Mode}$ , we construct the construction $\mathsf{B}(\mathsf{X})$	<b>LogiCRE</b>				<b>DUC/DDC Compiler</b>	xilinx.com:ip:duc_ddc_compiler:2.0
Bit-accurate C models for the core can be downloaded from the Xilinx DUC/DDC Compiler IP Core webpage.						
Details of how to use the models can be found in the C model user guide which accompanies the C models.		Frequency (kHz)			Phase Offset (radians)	
	Carrier 19 0	lideal	Quantized 0	Ideal	Quantized 0.000	
	Carrier 20 0		n		0.000	
	Carrier 21   C		n		0.000	
	Carrier 22 0		O		0.000	
	Carrier 23 0		U		0.000	
	Carrier 24 0		Ŭ		0.000	
	Carrier 25   0		0		0.000	
	Carrier 26 0		0		0.000 0.000	
	Carrier 27 0 Carrier 28 0		Ω Λ		0.000	
	Carrier 29 0		n		0.000	
	Carrier 30 0		Ù		0.000	

*Figure 7:* **GUI Page 4, with C Model Tab**

- **Carrier Specification Table:** The Carrier Specification Table presents the user with a set of text entry cells in which to specify ideal carrier frequencies and phase offsets, and a matching set of report text cells that report the closest achievable quantized equivalent of these ideal values.
- **Quantization:** This text box provides the user with information on the quantization units that can be expected when checking the Quantized cells in the Carrier Specification Table. The quantized values for frequency and phase are multiples of the specified quanta.
- **Programmable Carrier Frequencies:** Select the capability to re-program carrier frequencies via the programming port.
- **Programmable Carrier Gain Control:** Select the capability to scale carrier amplitudes prior to multi-carrier mixing by a programmable gain factor. This feature is only available for a DUC, and is limited to integer powers of 2 only, with a nominal maximum gain of 1.0  $(2^0)$  and a minimum positive gain of  $2^{-8}$ , with zero gain also available.

# **Using the DUC/DDC Compiler IP Core**

The GUI performs error-checking on all input parameter sets, applying range or value limitations as appropriate and providing feedback to the user to guide configuration. Resource estimation and approximate latency information are also available.

Several files are produced when a core is generated, and customized instantiation templates for Verilog and VHDL design flows are provided in the .veo and .vho files, respectively. For detailed instructions, see the Xilinx documentation.

### **Simulation Models**

The core has two options for simulation models:

- VHDL UNISIM-based structural simulation model
- Verilog UNISIM-based structural simulation model

The models required can be selected in the CORE Generator or Vivado project options. No behavioral HDL model is provided for the core.

# **General Information**

The DUC/DDC Compiler provides coverage of a wide range of parameters that affect the design implementation while presenting a simple interface to the user; detailed knowledge of the internal workings of the core are generally unnecessary. The core handles configuration by querying a compiled database of highly optimal design configurations, which provides configuration information on appropriate rate change steps, filter configurations and numbers of datapaths at each stage, mixer sample rate and configuration and flow control signal handling.

The basic static configuration parameter options for the core and their effects are detailed in the preceding GUI section, while the programming interface and registers define dynamic configuration options and their effects. Where some additional understanding of the core configuration and implementation is beneficial to ease integration of the core into an application system, further information is provided in this section.

The DUC/DDC Compiler makes extensive use of the FIR Compiler LogiCORE IP (v5.0) as a component core, including multiple instances of FIR filters in cascades to achieve the desired up- or down-conversion function. Familiarity with the data sheet for that core is advised to better understand some of the features of this core, particularly with regard to behavior under reset conditions. The implications of FIR filter reset behavior for overall DUC/DDC as a whole are described in [Filter Sample History Persistence.](#page-12-0)

### **Input Range**

The input data format is a binary word of user-configurable width with arbitrary scaling (nominally the range is considered as being between -1.0 and 0.99999...)

A further restriction must be considered when using an  $F_s/4$  IF mixer stage. In such cases, the input is saturated at -0.999... to 0.999... to avoid any increase in integer bit representation, as the  $F_s/4$  sampling operation utilizes a logical inversion stage, and therefore the data input signal must have a symmetrical range about zero. Saturation is performed within the core; however, users should be aware of this fact and might wish to scale input data appropriately to minimize the frequency and impact of that saturation operation.

### **Internal Range**

Integer bit growth can be introduced in filters and mixers, and the core accumulates these bits to maintain full accuracy (no saturation or scaling stages are inserted in the datapath processing chain.) Generally, the gain of the filters in the implemented cores is configured to maintain the dynamic range of the datapath (unity gain, or gain scaled by the rate change factor); however, some headroom is added in the initial filter stage, and DUC mixer stages introduce bit growth due to accumulation. The Data Format information in the GUI provides feedback on the number of integer bits at the output stage.

The output of each filter stage and each mixer operation is rounded using a "Convergent to Even" rounding scheme throughout. Internal data bit width representation retains as much precision as is practical. Overflow is handled by wrapping.

### **Output Range and Scaling**

Growth in the number of integer bits through the various filter stages and multi-carrier mixer accumulator is controlled to maintain a balance between likelihood of overflow and achieving sufficient precision to achieve the desired performance specified by the relevant air standard. The GUI provides a text field to indicate the output integer bits utilized by the current configuration. Generally, the core adds 1 additional integer bit for headroom and then the filter chain maintains unity gain as far as is practical; the main exception to this pattern is the case of multicarrier DUCs, in which case the mixer accumulation leads to additional integer bits.

### <span id="page-12-1"></span>**Rasterized DDS: Specification and Programming**

The multi-carrier mixing function uses an efficient form of Direct Digital Synthesizer which is commonly referred to as a "rasterized" DDS, in that it can only produce frequencies which fall on a "raster" of fixed frequency values separated by a constant frequency difference (the "raster step".) Wireless air interface standards generally have a specified raster of frequencies at which carriers can be located; for LTE, the minimum raster is 100 kHz, while for TD-SCDMA and W-CDMA it is 200 kHz. There are certain special cases included in the latest revisions of the W-CDMA and TD-SCDMA standards which call for a 100 kHz offset and therefore the lower 100 kHz figure is used as the base requirement for all cases. The raster step used in the DDS for the core depends on the desired mixing frequency, and is sometimes smaller than that specified in the wireless standard (the implementation raster step is in fact the greatest common divisor of the wireless standard raster and the mixing sample rate selected by the core.)

The frequency raster step is shown in the GUI in the Quantization section, see Pages  $3 \& 4$ . All carrier frequencies are multiples of this frequency raster. Quantization of carrier frequencies to make them multiples of the frequency raster is performed automatically by the GUI.

Users are highly recommended to restrict the range of carrier frequencies such that all carriers lie within the width of the IF Passband, centered at zero Hz. The filters in the core are designed for that range of carrier frequencies, and carriers outside this range are strongly attenuated.

### <span id="page-12-0"></span>**Filter Sample History Persistence**

The DUC/DDC core contains several internal FIR filter stages. Each filter stage has a sample history pipeline that contributes to the overall sample latency of the core. The core does not clear the contents of these pipelines at initialization and after reset events; therefore consistent operation is only guaranteed when these pipelines have flushed with known sample values, which takes several samples equal to the total sample latency, or, in other words, the impulse response length of the full filter cascade. The M\_AXIS\_DOUT\_TUSER signal denotes the period following reset and initialization during which time the sample history might be unknown, should that information be required. For further information on M\_AXIS\_DOUT\_TUSER timing behavior, see [Master Data Output Interface.](#page-17-0)

# **Control Signals and Timing**

The DUC/DDC Compiler v2.0 core has five interfaces:

- **System interface**: clock and reset signals
- **Data input interface**: AXI4-Stream slave
- **Data output interface**: AXI4-Stream master
- **Programming interface**: AMBA 3 APB slave
- **Interrupt interface**: interrupt output signals

### **System Interface**

The system interface consists of a single clock and a single synchronous reset.

All interfaces and all internal logic use the same single clock, ACLK.

The synchronous reset input ARESETN is active-Low, and applies to the datapath, the data input interface, the data output interface, and the interrupt interface. A second reset input, SREG\_PRESETn, is provided for resetting the programming interface and registers: see the [Programming Interface](#page-19-0) section. Both reset inputs are present only when "Optional Pins - Reset" is selected in the GUI.

#### <span id="page-13-0"></span>**Slave Data Input Interface**

The slave data input interface is an AXI4 compliant data streaming interface that receives data samples that are to be input to the core. The core asserts S\_AXIS\_DIN\_TREADY when it is ready to receive a data sample. S\_AXIS\_DIN\_TVALID input indicates that the input data is valid. Data is input into the core when both S\_AXIS\_DIN\_TREADY and S\_AXIS\_DIN\_TVALID are asserted.

After reset, when the core is ready to receive the first input data sample set, the core holds S\_AXIS\_DIN\_TREADY high until S\_AXIS\_DIN\_TVALID goes high to indicate the first input data sample. Thereafter, the core expects input data to be provided at a steady rate, and it indicates the expected data rate by asserting S\_AXIS\_DIN\_TREADY. If input data is not provided at the expected time (S\_AXIS\_DIN\_TREADY is high but S\_AXIS\_DIN\_TVALID is low), then the core holds S\_AXIS\_DIN\_TREADY high until S\_AXIS\_DIN\_TVALID goes high, and signals a missing input interrupt on the INT\_MISSINPUT interrupt output. The core continues to process and output data that is in its datapath while it waits for new data. There is a corresponding pause in the output data rate when data in the core datapath has been output from the core.

The data bus input to the core, S\_AXIS\_DIN\_TDATA, is an amalgamated bus formed by concatenation of individual data samples, covering all antennas and including both In-phase and Quadrature sample values where appropriate.

Depending on the core configuration, the data is input in one of three ways:

DDC cores with Digital IF set to  $F_s/4$ 

Real only input data from each antenna is sign-extended to the nearest byte boundary and concatenated together from lowest antenna number in the LS position to highest antenna number in the MS position.





• Any DUC core, or a DDC core with Digital IF set to Zero, and parallel I and Q signal format selected

Complex input data, with in-phase (I) and quadrature (Q) portions sign-extended separately, then concatenated with I least significant and Q most significant, concatenated together from lowest antenna number in the LS position to highest antenna number in the MS position.



#### *Figure 9:* **DUC/DDC Core with Digital IF set to Zero and Parallel I, Q Signal Format**

• Any DUC core, or a DDC core with Digital IF set to Zero, and TDM mode I and Q signal format selected

Complex input data, with in-phase and quadrature portions sign-extended in a TDM (alternating) format, and concatenated together from lowest antenna number in the LS position to highest antenna number in the MS position.



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*Figure 10:* **DUC/DDC Core with Digital IF set to Zero, TDM mode I, Q Signal Format**

The minimum TDATA width that could occur is in the case of a single antenna, single carrier TDM input format DUC, or a single antenna DDC with either TDM input format or digital IF at  $F_s/4$  (real data only). In such cases, using the minimum constituent data unit width of 11, sign-extension to the next byte boundary results in a data to 16. The maximum TDATA width that could occur is in the case of a full complement of 8 antennas, parallel I/Q input/output format DUC. In such cases, using the maximum constituent data unit width of 17, sign-extended to 24 bits, the output width would be  $8 \times 2 \times 24 = 384$ .

S\_AXIS\_DIN\_TLAST input indicates the last sample of an input packet: this is the input data sample for the last carrier (in a multi-carrier DUC), the quadrature portion if TDM format is used. The core expects input data to be provided for each carrier in ascending carrier order (in a multi-carrier DUC), and in-phase then quadrature data if TDM format is used. If S\_AXIS\_DIN\_TLAST is asserted for any sample other than the last sample of an input packet, or is not asserted for the last sample of an input packet, then the core ignores S\_AXIS\_DIN\_TLAST and signals a packet error interrupt on the INT\_ERRPACKET interrupt output. It is not possible to change the input sample order using S\_AXIS\_DIN\_TLAST. A DDC or a single carrier DUC with Data Interface Format of separate I and Q signals has an input packet containing only one sample: in this configuration, S\_AXIS\_DIN\_TLAST is not present.

### **Timing Diagrams**

[Figure 11,](#page-16-0) [Figure 12,](#page-16-1) [Figure 13](#page-16-2) and [Figure 14](#page-16-3) show timing diagrams for four configurations of the core:

- [Figure 11:](#page-16-0) DDC with Digital IF of  $F<sub>s</sub>/4$ , real data input, 1 antenna
- [Figure 12](#page-16-1): DDC with Digital IF of 0 Hz, TDM format, 1 antenna
- [Figure 13](#page-16-2): DUC with 3 carriers, separate I and Q format, 1 antenna
- [Figure 14](#page-16-3): DUC with 3 carriers, TDM format, 1 antenna

In each case, the input packet is 8 clock cycles in length. The effects of S\_AXIS\_DIN\_TVALID not being high when S\_AXIS\_DIN\_TREADY is high causing a missing input interrupt, and incorrect S\_AXIS\_DIN\_TLAST (where present) causing a packet error interrupt, are shown towards the end of each timing diagram. Interrupt signals are asserted 2 clock cycles after the interrupt event.

<span id="page-16-1"></span><span id="page-16-0"></span>

<span id="page-16-3"></span><span id="page-16-2"></span>

### <span id="page-17-0"></span>**Master Data Output Interface**

The master data output interface is an AXI4 compliant data streaming interface that outputs data samples from the core. The core asserts M\_AXIS\_DOUT\_TVALID when new output data is valid and presented on the interface. The core holds M\_AXIS\_DOUT\_TVALID high until M\_AXIS\_DOUT\_TREADY is asserted. Data is output from the core when both M\_AXIS\_DOUT\_TVALID and M\_AXIS\_DOUT\_TREADY are asserted.

At reset and initialization, the core holds M\_AXIS\_DOUT\_TVALID low until input data has been received and processed by the core datapath, and is ready to be output. Thereafter, the core attempts to output data at a steady rate, and it asserts M\_AXIS\_DOUT\_TVALID when each output sample is available.

If input data was not provided at the slave data input interface when the core expected it, the core waits until input data is provided, but continues to process and output data that is in its datapath. When all data samples in the datapath have been output, the core holds M\_AXIS\_DOUT\_TVALID low until new input data has been received and processed by the core datapath, and is ready to be output. This results in a pause in the steady rate of output data. The core indicates that this happens by signalling a missing input interrupt on the INT\_MISSINPUT interrupt output when the input data was not provided at the expected time.

The core cannot accept back pressure. It must produce output samples at the rate determined by the input data rate and the sample rate change performed by the core. If M\_AXIS\_DOUT\_TVALID is high but M\_AXIS\_DOUT\_TREADY is held low, then any future output samples that the core generates is internally discarded, and the core signals a lost output interrupt on the INT\_LOSTOUTPUT interrupt output. Slaves are recommended to tie M\_AXIS\_DOUT\_TREADY high.

Similarly to the slave input data bus, S\_AXIS\_DIN\_TDATA, the data bus output from the core, M\_AXIS\_DOUT\_TDATA, is an amalgamated bus formed by concatenation of individual data samples, covering all antennas and including both In-phase and Quadrature sample values where appropriate.

Parallel I and Q signal format selected

Complex output data, with in-phase (I) and quadrature (Q) portions sign-extended separately, then concatenated with I least significant and Q most significant, concatenated together from lowest antenna number in the LS position to highest antenna number in the MS position.

TDM mode I and Q signal format selected

Complex input data, with in-phase (I) and quadrature (Q) portions sign-extended in a TDM (alternating, I first) format, and concatenated together from lowest antenna number in the LS position to highest antenna number in the MS position.

MDATA\_LAST output indicates the last sample of an output packet: this is the output data sample for the last carrier (in a multi-carrier DDC), the quadrature portion if TDM format is used. A DUC or a single carrier DDC with Data Interface Format of separate I and Q signals has an output packet containing only one sample: in this configuration, MDATA\_LAST is not present.

#### **Timing Diagrams**

[Figure 15](#page-18-0), [Figure 16](#page-18-1), [Figure 17](#page-18-2) and [Figure 18](#page-18-3) show timing diagrams for four configurations of the core:

- [Figure 15](#page-18-0): DUC with separate I and Q format, 1 antenna
- [Figure 16](#page-18-1): DUC with TDM format, 1 antenna
- [Figure 17](#page-18-2): DDC with 3 carriers, separate I and Q format, 1 antenna
- [Figure 18](#page-18-3): DDC with 3 carriers, TDM format, 1 antenna

In each case, the output packet is 8 clock cycles in length. The effect of M\_AXIS\_DOUT\_TREADY being held low for long enough to cause a lost output interrupt is shown towards the end of each timing diagram. Interrupt signals are asserted 2 clock cycles after the interrupt event.

<span id="page-18-0"></span>

*Figure 15:* **Master Data Input Interface Timing Diagram: DUC, Separate I and Q Format, 1 Antenna**

<span id="page-18-1"></span>

*Figure 16:* **Master Data Input Interface Timing Diagram: DUC, TDM Format, 1 Antenna**

<span id="page-18-2"></span>



<span id="page-18-3"></span>



### <span id="page-19-0"></span>**Programming Interface**

The programming interface is an AMBA 3 APB slave interface for programming carrier frequencies and carrier gain control for providing configuration, status and error information about the core. The programming interface is always present.

The programming interface complies with the AMBA 3 APB interface specification [\[Ref 8\]](#page-36-0). See this specification for detailed information about the interface.

The core uses SREG\_PREADY to insert wait states to extend APB transactions. All transactions on the programming interface use at least 3 wait states. Reads and writes to "Frequency Programming Registers" and "Gain Control Programming Registers" sometimes use more wait states, up to a maximum of 9.

SREG\_PRESETn is the reset signal for the programming interface and registers. This reset signal is synchronous and active-Low. SREG\_PRESETn is registered internally to aid timing closure, and takes effect one cycle after it is synchronously asserted.

### **Interrupt Interface**

The interrupt interface is a set of interrupt output pins, each corresponding to a particular interrupt type, plus one combined interrupt output pin that indicates an interrupt of any type:

- INT\_MISSINPUT indicates a missing input interrupt, see [Slave Data Input Interface](#page-13-0) for details and timing diagrams.
- INT\_ERRPACKET indicates an input packet length error interrupt, see [Slave Data Input Interface](#page-13-0) for details and timing diagrams.
- INT\_LOSTOUTPUT indicates a lost output interrupt, see [Master Data Output Interface](#page-17-0) for details and timing diagrams.
- INT\_DUCDDC indicates an interrupt of any type, and is the logical OR of the three interrupt signals above.

Interrupt signals are asserted 2 clock cycles after the corresponding interrupt event.

All interrupt outputs are always present. Each interrupt type can be independently enabled or disabled using the "Interrupt Enable Register". When an interrupt is disabled, the corresponding interrupt signal is held low at all times, whether an interrupt has occurred or not. INT\_DUCDDC cannot be independently enabled or disabled: it is the logical OR of the other three interrupt signals, and therefore takes into account the individual interrupt enables.

The current status of interrupts and interrupt signals is also available in the [Raw Interrupt Status Register](#page-26-0) and [Masked Interrupt Status Register](#page-26-1) respectively.

All interrupt outputs are sticky, and when they go high they stay high until disabled by writing to the [Interrupt](#page-26-2) [Enable Register,](#page-26-2) or cleared by writing to the [Interrupt Clear Register](#page-26-3) or resetting the core by asserting ARESETN.

# **Programming Interface Registers**

### **Register Map**

For compatibility with SoCs that use APB to communicate with several peripherals, the DUC/DDC Compiler register map is limited to a 4KB (12-bit) address space, and the address bus, SREG\_PADDR, is 12 bits wide.

<span id="page-20-0"></span>The DUC/DDC Compiler's register map is shown in [Figure 19.](#page-20-0)





### **Register Definitions**

The registers are summarized in [Table 3](#page-20-1), and described in detail in the following sections. All registers are 32 bits wide.



#### <span id="page-20-1"></span>*Table 3:* **Registers**



#### *Table 3:* **Registers** *(Cont'd)*

<span id="page-21-0"></span>1. Register is not reset by SREG\_PRESETn input.

<span id="page-21-1"></span>2. Initial value is calculated by the core based on several parameters.

<span id="page-21-2"></span>3. Initial value of each register <*n*> is the quantized carrier frequency for carrier <*n*> divided by the frequency raster.

<span id="page-21-3"></span>4. Initial value of each register <*n*> is the quantized carrier phase offset for carrier <*n*> divided by the phase raster.

If Programmable Carrier Frequencies is enabled, the Frequency Programming Registers are read/write; otherwise these registers are read only and an attempt to write them results in a SLVERR response.

If Programmable Carrier Gain Control is enabled, the Gain Control Programming Registers are read/write; otherwise they are read only and an attempt to write them results in a SLVERR response.

### **Lock Register**

<span id="page-22-0"></span>The Lock Register is a 32-bit read/write register at address 0x000 that enables or disables write access to all other registers accessible through the programming interface. The format of this register is shown in [Figure 20](#page-22-0).



*Figure 20:* **Lock Register**

The register bits are shown in [Table 4.](#page-22-1)



<span id="page-22-1"></span>*Table 4:* **Lock Register Bits**

Writes to the Lock Register are not affected by the L bit. Writes with an incorrect key (neither the lock nor unlock key) are silently ignored and do not affect the L bit. This register is reset by the SREG\_PRESETn reset input.

#### <span id="page-22-4"></span>**Programming Bank Selection Register**

<span id="page-22-2"></span>The Programming Bank Selection Register is a 32-bit read/write register at address 0x004 that selects the bank of programming registers to be active. The format of this register is shown in [Figure 21.](#page-22-2)



*Figure 21:* **Programming Bank Selection Register**

The register bits are shown in [Table 5.](#page-22-3)

<span id="page-22-3"></span>*Table 5:* **Programming Bank Selection Register Bits**

Bit	<b>Field</b>	Tvpe	Init	<b>Description</b>
[31:1]		-		Should Be Zero
		RW		Bank selection: $0 =$ programming registers bank A is active, bank B is shadowing. 1 = programming registers bank B is active, bank A is shadowing.

There are two banks of programming registers – bank A and bank B. Each bank of registers contains a complete set of frequency, phase offset, and gain programming registers (see [Frequency Programming Registers,](#page-27-0) [Phase Offset](#page-28-0) [Programming Registers](#page-28-0) and [Gain Control Programming Registers](#page-28-1) respectively.) At any time, one bank of programming registers is active and the other bank is shadowing, allowing rapid updating "on-the-fly". The active bank is used by the core datapath, and is read only; writes to registers in the active bank result in a SLVERR response. The shadowing bank is not used by the core datapath, and is read/write, so can be used for programming new frequency, phase offset, and gain values. When the new values are correctly programmed in the shadowing bank, write the Programming Bank Selection Register to change the B bit, and the new values become the active bank and are used by the core datapath. This register is not reset by the SREG\_PRESETn reset input.

Users wishing to update only a single register value can do so in a few register transactions, by writing to the programming register to switch banks, then writing the new register value, then finally switching banks back again. This should only be attempted while the core is not actively transmitting or receiving (for example, during an interslot gap), as the core uses the configuration data in the alternate bank during the register write transaction time.

Any write to the Programming Bank Selection Register, whether the value of the B bit is changed or not, forces an internal core datapath reset, as if ARESETN had been asserted. This is required to allow the DDS and mixer to start using the new programmed frequency, phase offset and gain values in a consistent and predictable manner. The M\_AXIS\_DOUT\_TVALID signal goes low to indicate that the core has been reset, and remains low until new input data has been processed and has propagated through the core. The internal datapath reset does not clear the contents of internal sample history pipelines. See [Filter Sample History Persistence](#page-12-0) for the implications of this on output data values.

#### <span id="page-23-2"></span>**Configuration Register**

<span id="page-23-0"></span>The Configuration Register is a 32-bit read only register at address 0x080 that shows the value of key core parameters. The format of this register is shown in [Figure 22](#page-23-0).

104	28 27 26 25		20 19		16 15 14 13 12 11		
SB 2		ВW		ם וב/ו			

*Figure 22:* **Configuration Register**

The register bits are shown in [Table 6.](#page-23-1)

<span id="page-23-1"></span>*Table 6:* **Configuration Register Bits**

<b>Bit</b>	<b>Field</b>	<b>Type</b>	<b>Description</b>
[31:28]			Should Be Zero
[27:26]	IF	<b>RO</b>	Digital IF: 00: 0 Hz 01: $F_s/4$ All other values are reserved.
[25:20]	<b>BW</b>	RO	Channel bandwidth option, also depends on S field. See Table 7 for details.
[19:16]	S	RO.	Wireless standard: 0000: LTE 0001: TD-SCDMA 0010: W-CDMA All other values are reserved.
15	т	<b>RO</b>	Core type: 0: DUC 1: DDC
14	G	<b>RO</b>	Programmable gain control: $0 = no programmable gain control$ $1 =$ programmable gain control present
13	P	RO.	Programmable carrier phase offsets. Reserved for future use; always reads as zero.



#### *Table 6:* **Configuration Register Bits** *(Cont'd)*

The channel bandwidth is determined from the S and BW fields as shown in [Table 7](#page-24-0). All combinations of S and BW not shown are reserved. There are two settings for the same bandwidth for each of TD-SCDMA and W-CDMA; the latter setting is associated with DDC cores only, and indicates a baseband sample rate at twice the chip rate.

<span id="page-24-0"></span>*Table 7:* **Channel Bandwidth**

$\mathbf{s}$	<b>Wireless Standard</b>	<b>BW</b>	<b>Channel Bandwidth</b>
		000001	$1.4$ MHz
		000011	3 MHz
0000	LTE	000101	5 MHz
		001010	10 MHz
		001111	15 MHz
		010100	20 MHz
0001	<b>TD-SCDMA</b>	000010	1.6 MHz
		000110	1.6 MHz (2 x $F_{sym}$ )
0010	W-CDMA	000100	5 MHz
		001000	5 MHz (2 $\times$ F <sub>sym</sub> )

The C field, which reports the number of carriers, is expected to be the most used, to allow driver software to generate programmable carrier frequencies and gains. Therefore this field is in the LSBs of the register so that a register read and a single AND **0x3F** software instruction can return the number of carriers.

The value of this register is constant and does not change during run time.

#### <span id="page-24-3"></span>**Mixing Rate Multiple Register**

<span id="page-24-2"></span>The Mixing Rate Multiple Register is a 32-bit read only register at address 0x084 that indicates the ratio between the mixing sample rate and the frequency raster. It shows the number of possible carrier positions for both carrier frequency and carrier phase offset. The format of this register is shown in [Figure 23](#page-24-2).



*Figure 23:* **Mixing Rate Multiple Register**

The register bits are shown in [Table 8.](#page-24-1)

<span id="page-24-1"></span>*Table 8:* **Mixing Rate Multiple Register Bits**

<b>Bit</b>	Field	<b>VDE</b>	<b>Description</b>	
[31:0]	mrm	<b>RO</b>	Mixina .g Rate Multiple, unsigned integer value	

The mixing rate multiple (mrm) indicates the number of possible values for carrier frequency and carrier phase offset. Carrier frequency values in [Frequency Programming Registers](#page-27-0) are in the range -mrm/2 to mrm/2-1. Carrier phase offset values in [Phase Offset Programming Registers](#page-28-0) are in the range 0 to mrm-1.

The phase raster can be calculated from the mixing rate multiple using the formula:

phase raster (radians) = 2 $\pi$  / mrm

The sample rate at which multi-carrier mixing occurs can be calculated from the mixing rate multiple and the frequency raster (see [Frequency Raster Register](#page-25-1)) using the formula:

mixing sample rate in  $Hz$  = frequency raster in  $Hz \times mrm$ 

The value of this register is constant and does not change during run time.

#### <span id="page-25-1"></span>**Frequency Raster Register**

<span id="page-25-2"></span>The Frequency Raster Register is a 32-bit read only register at address 0x088 that indicates the frequency raster in Hz for the implemented wireless standard. The format of this register is shown in [Figure 24](#page-25-2).



#### *Figure 24:* **Frequency Raster Register**

The register bits are shown in [Table 9.](#page-25-0)

#### <span id="page-25-0"></span>*Table 9:* **Frequency Raster Register Bits**



See [Rasterized DDS: Specification and Programming](#page-12-1) for details of the frequency raster.

The value of this register is constant and does not change during run time.

#### **Interrupt Registers**

There are four interrupt registers:

- [Interrupt Enable Register](#page-26-2)
- [Masked Interrupt Status Register](#page-26-1)
- [Raw Interrupt Status Register](#page-26-0)
- **[Interrupt Clear Register](#page-26-3)**

<span id="page-25-3"></span>All four registers have the same format, which is shown in [Figure 25.](#page-25-3)



*Figure 25:* **Interrupt Registers**

Each field in the interrupt registers corresponds to an interrupt type, as shown in [Table 10.](#page-26-4)



#### <span id="page-26-4"></span>*Table 10:* **Interrupt Register Bits**

#### <span id="page-26-2"></span>*Interrupt Enable Register*

The Interrupt Enable Register is a 32-bit read/write register at address 0x0A0 that enables or disables interrupts. The format and register bits are shown in [Figure 25](#page-25-3) and [Table 10.](#page-26-4)

When a bit in the Interrupt Enable Register is set, the interrupt for that bit is enabled, and an interrupt shown in the Raw Interrupt Status Register is also signalled by the corresponding interrupt output going high. Clearing a bit disables the interrupt for that bit, and the corresponding interrupt is masked (the interrupt output is held low) regardless of the interrupt status.

All interrupts are enabled (all bits corresponding to interrupts are 1) at reset. This register is reset by the SREG\_PRESETn reset input.

#### <span id="page-26-1"></span>*Masked Interrupt Status Register*

The Masked Interrupt Status Register is a 32-bit read only register at address 0x0A4 that provides the interrupt status taking into account interrupt enabling. This is the AND of the Raw Interrupt Status Register and the Interrupt Enable Register. The Masked Interrupt Status Register directly indicates the status of the interrupt output pins. The format and register bits are shown in [Figure 25](#page-25-3) and [Table 10](#page-26-4).

When a bit in the Masked Interrupt Status Register is high, the interrupt for that bit is triggered and enabled. When a bit is low, the interrupt for that bit is either not triggered or is not enabled, and so has been masked.

All bits are 0 initially. This register is not reset by the SREG\_PRESETn reset input. Interrupts are reset (cleared) by the ARESETN reset input, and the Interrupt Enable Register is reset by the SREG\_PRESETn reset input; therefore this register can change value on either reset.

#### <span id="page-26-0"></span>*Raw Interrupt Status Register*

The Raw Interrupt Status Register is a 32-bit read only register at address 0x0A8 that provides the interrupt status ignoring interrupt enabling. The Raw Interrupt Status Register indicates the status of interrupts from the core before masking. The Raw Interrupt Status Register can differ from the status of the interrupt output pins if one or more interrupts are disabled using the Interrupt Enable Register. The format and register bits are shown in [Figure 25](#page-25-3) and [Table 10.](#page-26-4)

When a bit in the Raw Interrupt Status Register is high, the interrupt for that bit is triggered. When a bit is low, the interrupt for that bit is not triggered.

All bits are 0 initially. This register is not reset by the SREG\_PRESETn reset input. Interrupts are reset (cleared) by the ARESETN reset input; therefore this register might change value on ARESETN.

#### <span id="page-26-3"></span>*Interrupt Clear Register*

The Interrupt Clear Register is a 32-bit write only register at address 0x0AC for clearing interrupts. The format and register bits are shown in [Figure 25](#page-25-3) and [Table 10.](#page-26-4)

Writing 1 to a bit in the Interrupt Clear Register clears the corresponding bit in the Raw Interrupt Status Register, thereby clearing the interrupt and setting the corresponding interrupt output pin low. Writing 0 to a bit has no effect.

#### <span id="page-27-0"></span>**Frequency Programming Registers**

The Frequency Programming Registers are two banks, bank A and bank B, of C 32-bit read/write registers, where C is the number of carriers (reported in the C field of the [Configuration Register.](#page-23-2)) The registers in bank A are at sequential word addresses starting at address 0x100; the registers in bank B are at sequential word addresses starting at address 0x500. The a\_frequency<*n*> register for carrier *n* is at address  $(0x100 + 4 \times (n - 1))$ , and the b\_frequency<*n*> register for carrier *n* is at address (0x500 + 4 × (*n* - 1)). Each a\_frequency<*n*> and b\_frequency<*n*> register holds the frequency for carrier *n* as a multiple of the frequency raster, given by the [Frequency Raster](#page-25-1) [Register](#page-25-1).

<span id="page-27-2"></span>The format of each a\_frequency<*n*> and b\_frequency<*n*> register is shown in [Figure 26.](#page-27-2)



*Figure 26:* **a\_frequency<***n***> and b\_frequency<***n***> Registers**

The register bits are shown in [Table 11](#page-27-3).

<span id="page-27-3"></span>*Table 11:* **a\_frequency<***n***> and b\_frequency<***n***> Register Bits**

Bit	Field	Type	Init	<b>Description</b>
[31:0]	frequency	RW		Carrier n frequency as a multiple of the frequency raster. 2's complement integer in the range - <i>mrm</i> /2 to <i>mrm</i> /2-1, where <i>mrm</i> is the mixing rate multiple, see Mixing Rate Multiple Register.

<span id="page-27-1"></span>1. Initial value of each register <*n*> is the quantized carrier frequency for carrier <*n*> divided by the frequency raster.

Software drivers can calculate the correct value to write to a Frequency Programming Register using the required frequency in Hz and the frequency raster; see [Frequency Raster Register.](#page-25-1)

frequency programming value = required frequency in Hz / frequency raster in Hz

The [Programming Bank Selection Register](#page-22-4) selects which bank of Frequency Programming Registers is active (used by the core datapath) and which is shadowing (not used by the core datapath but available for programming.) Frequency Programming Registers in the active bank are read only – an attempt to write an active bank Frequency Programming Register results in a SLVERR response. Frequency Programming Registers in the shadowing bank are read/write if Programmable Carrier Frequencies is enabled, and read only otherwise. Values written to Frequency Programming Registers in the shadowing bank are not used by the core datapath until the Programming Bank Selection Register is modified to swap the active and shadowing banks.

An attempt to write a Frequency Programming Register with a value that is out of the legal range results in a SLVERR response and does not change the register value. An attempt to read or write a Frequency Programming Register that does not exist (that is, where *n* is greater than the number of carriers) results in a SLVERR response.

For a single carrier, the single Frequency Programming Register in each bank is read only and its value is set to zero.

These registers are *not* reset by the SREG\_PRESETn reset input.

#### <span id="page-28-0"></span>**Phase Offset Programming Registers**

The Phase Offset Programming Registers are two banks, bank A and bank B, of C 32-bit read only registers, where C is the number of carriers (reported in the C field of the [Configuration Register.](#page-23-2)) The registers in bank A are at sequential word addresses starting at address 0x200; the registers in bank B are at sequential word addresses starting at address 0x600. The a\_phase<*n*> register for carrier *n* is at address (0x200 + 4 × (*n* - 1)), and the b\_phase<*n*> register for carrier *n* is at address (0x600 + 4 × (*n* - 1)). Each a\_phase<*n*> and b\_phase<*n*> register holds the phase offset for carrier *n* as a multiple of the phase raster, which can be calculated from the [Mixing Rate Multiple](#page-24-3) [Register](#page-24-3).

<span id="page-28-3"></span>The format of each a\_phase< $n$ > and b\_phase< $n$ > register is shown in [Figure 27](#page-28-3).



*Figure 27:* **a\_phase<***n***> and b\_phase<***n***> Registers**

The register bits are shown in [Table 12.](#page-28-4)

<span id="page-28-4"></span>*Table 12:* **a\_phase<***n***> and b\_phase<***n***> Register Bits**

<b>Bit</b>	<b>Field</b>	Type	Init	<b>Description</b>
[31:0]	phase	R <sub>O</sub>		Carrier n phase offset as a multiple of the phase raster. Unsigned linteger in the range 0 to mrm-1, where mrm is the mixing rate multiple, see Mixing Rate Multiple Register.

<span id="page-28-2"></span>1. Initial value of each register <*n*> is the quantized carrier phase offset for carrier <*n*> divided by the phase raster.

The value of a Phase Offset Programming Register is calculated from the corresponding carrier phase offset in radians and the phase raster, which is derived from the mixing rate multiple, see [Mixing Rate Multiple Register](#page-24-3).

Phase Offset Programming Register value = carrier phase offset in radians / phase raster in radians

All Phase Offset Programming Registers in both bank A and bank B are read only. Carrier phase offsets cannot be changed at run time.

#### <span id="page-28-1"></span>**Gain Control Programming Registers**

The Gain Control Programming Registers are two banks, bank A and bank B, of C 32-bit read/write registers, where C is the number of carriers (reported in the C field of the [Configuration Register.](#page-23-2)) The registers in bank A are at sequential word addresses starting at address 0x300; the registers in bank B are at sequential word addresses starting at address 0x700. The a\_gain<*n*> register for carrier *n* is at address (0x300 + 4 × (*n* - 1)), and the b\_gain<*n*> register for carrier *n* is at address  $(0x700 + 4 \times (n-1))$ . Each a\_gain<*n*> and b\_gain<*n*> register holds the gain for carrier *n*.

<span id="page-28-5"></span>The format of each a\_gain<*n*> and b\_gain<*n*> register is shown in [Figure 28](#page-28-5).



*Figure 28:* **a\_gain<***n***> and b\_gain<***n***> registers**

The register bits are shown in [Table 13.](#page-29-1)



<span id="page-29-1"></span>

Gain control allows the relative amplitude of carriers to be adjusted, for example for power management, by attenuating one or more carriers. Each carrier's amplitude is attenuated by the programmed value. For example, writing a gain value of 001000000 to carrier 1 Gain Control Programming Register corresponds to a gain of 0.25, and all data values for carrier 1 are multiplied by 0.25 prior to multi-carrier mixing.

The [Programming Bank Selection Register](#page-22-4) selects which bank of Gain Control Programming Registers is active (used by the core datapath) and which is shadowing (not used by the core datapath but available for programming.) Gain Control Programming Registers in the active bank are read only – an attempt to write an active bank Gain Control Programming Register results in a SLVERR response. Gain Control Programming Registers in the shadowing bank are read/write if Programmable Carrier Gain Control is enabled, and read only otherwise. Values written to Gain Control Programming Registers in the shadowing bank are not used by the core datapath until the Programming Bank Selection Register is modified to swap the active and shadowing banks.

An attempt to write a Gain Control Programming Register with an illegal value or with a value that is out of the legal range results in a SLVERR response and does not change the register value. An attempt to read or write a Gain Control Programming Register that does not exist (that is, where *n* is greater than the number of carriers) results in a SLVERR response.

For a single carrier, the single Gain Control Programming Register in each bank is read only and its value is set to 100000000 (that is, 1.0).

Gain control is not available for DDCs: all Gain Control Programming registers are read only in DDCs.

These registers are *not* reset by the SREG\_PRESETn reset input.

# <span id="page-29-0"></span>**Performance and Resource Utilization**

Resource requirements and performance are dependent on a wide range of core parameters, but mainly on these factors: difference in input and output sample rates; number of carriers; and number of antennas. The last of these options has the largest impact, as the resource usage of the core is almost linear with respect to this value (actually slightly less due to certain resource sharing between antenna datapaths and a single programming interface and register set.)

[Table 14,](#page-31-0) [Table 15](#page-33-0), [Table 16,](#page-34-0) and [Table 17](#page-35-0) provide resource requirements for Virtex®-7, Virtex-6, Virtex-5 and Kintex-7 devices, respectively. For all configurations, the default data width of 16-bits is used at both data input and output interfaces.

The results are obtained by double-registering input and output ports to reduce dependence on I/O placement. The inner level of registers use a separate clock signal to measure the path from the input registers to the first output register through the core.

The resource usage results do not include these double registers on inputs and outputs, and represent the true logic used by the core to implement a single instance. LUT counts include SRL16s or SRL32s (according to device family.) Each configuration is constrained to achieve the target clock frequency, including 300 ps total peak-to-peak clock jitter margin (sufficient for most clock sources used in FPGAs.)

Results are obtained using Xilinx ISE Design Suite 14.3 - similar results should be achieved when using the core within the Vivado Design Suite.

The map options used are: map  $-pr$  b  $-ol$  high

The par options used are: par -ol high

The achievable clock frequency and the resource counts might also be affected by other tool options, routing congestion due to additional logic in the FPGA, using a different version of Xilinx tools, and other factors. No advanced constraint usage is employed in achieving these results. Area group constraints and other enhanced placement techniques might improve performance and further reduce area, or allow the use of a lower speed grade.

To aid timing closure, inputs are immediately registered inside the core where possible, and all outputs are driven directly from registers. The handshaking protocol in the slave data input interface requires S\_AXIS\_DIN\_TVALID to be used in combinatorial logic without registering it, so this input needs additional timing slack.

#### *Core Optimization: Area versus Speed*

The DUC/DDC Compiler can generate a wide range of core configurations targeted at different device families with different sub-types and speed grades. Unfortunately, it is not possible to characterize the performance and resource usage of all permutations. Consequently, the performance tables are only an indication. The core includes some implementation options to allow users to tailor the core for their device or application.

The selection of "Area" or "Speed" for the Optimization Goal option is an additional measure for customers who experience difficulty in achieving the desired timing for the core in their device. Normally, the goal should be kept as "Area", the default setting, as this normally achieves good timing results. However, there are certain combinations of device and core configuration that might result in the core failing to achieve the timing goal without intervention. If the device resource levels allow, the "Speed" setting for Optimization Goal adds additional logic resources to try to improve the chances of achieving the desired timing in the target device.

#### *Guidance on Suitable Device Selection*

One significant factor in achieving the desired timing performance is the availability of DSP slices and DSP slice column separation within the targeted device. This is due to the use of filter modules within the DUC or DDC architectures because filters make extensive use of cascaded DSP slices to implement efficient filter structures. The SX devices have a high ratio of DSP slices to logic, and many columns with low separation distances. This is in contrast to other Virtex devices (for example, LX and FX) that contain a lower ratio of DSP slices to logic, and fewer columns with greater separation distances. For large DUC or DDC designs, there is a greater chance that the core resources are spread over multiple DSP slice columns. As a result, it is easier to achieve timing closure in SX devices than LX devices due to the shorter distances between columns.

Customers who attempt to implement a larger core in an LX device and cannot achieve the desired core timing have some options for alleviating the timing issue. One option is to set the Optimization Goal option to "Speed", which adds some additional logic targeted at increasing the chances of achieving timing closure, at the expense of increased resource usage. Another option is to implement fewer antennas in a single core and use multiple core instances to create all the antenna datapaths. Each core instance can then be constrained by an Area Group to achieve the desired timing. The only disadvantage in splitting up the antennas across several core implementations is duplication of the resources used for the DDS module and APB peripheral bus interface. However, these are generally a relatively small portion of the overall resources for each core.

# **Resource Utilization (Virtex-7)**

[Table 14](#page-31-0) provides characterization data for Virtex-7 FPGAs using a VC7VX330T device in a FFG1761 package; the speed grade and optimization setting required is indicated for each configuration. Block RAM counts listed are for 18K blocks, which are often amalgamated into pairs for mapping to 36K locations where possible; it is important to note this when comparing these values with map results for your configuration.

<span id="page-31-0"></span>







1. Clock frequency determined using 300ps peak-to-peak clock jitter allowance

2. Entries with 2x in the Channel Bandwidth column use over-sampled output rate of twice the standard symbol rate

### **Resource Utilization (Virtex-6)**

[Table 15](#page-33-0) provides characterization data for Virtex-6 FPGAs using a XC6VSX315T device in a FF1759 package; the speed grade and optimization setting required is indicated for each configuration. Block RAM counts listed are for 18K blocks, which are often amalgamated into pairs for mapping to 36K locations where possible; it is important to note this when comparing these values with map results for your configuration.

<span id="page-33-0"></span>



1. Clock frequency determined using 300ps peak-to-peak clock jitter allowance

2. Entries with 2x in the Channel Bandwidth column use over-sampled output rate of twice the standard symbol rate

### **Resource Utilization (Virtex-5)**

[Table 16](#page-34-0) provides characterization data for Virtex-5 FPGAs using a XC5VSX240T device in a FF1738 package; the speed grade and optimization setting required is indicated for each configuration. Block RAM counts listed are for 18K blocks, which are often amalgamated into pairs for mapping to 36K locations where possible; it is important to note this when comparing these values with map results for your configuration.



<span id="page-34-0"></span>

1. Clock frequency determined using 300ps peak-to-peak clock jitter allowance

2. Entries with 2x in the Channel Bandwidth column use over-sampled output rate of twice the standard symbol rate

## **Resource Utilization (Kintex-7)**

[Table 17](#page-35-0) characterization data for Kintex™-7 FPGAs using an XC7K325T device in an FFG900 package; the speed grade and optimization setting required is indicated for each configuration. Block RAM counts quoted are for 18K blocks, which are often amalgamated into pairs for mapping to 36K locations where possible; it is important to note this when comparing these values with map results for your configuration.

<span id="page-35-0"></span>



1. Clock frequency determined using 300ps peak-to-peak clock jitter allowance

2. Entries with 2x in the Channel Bandwidth column use over-sampled output rate of twice the standard symbol rate

## **References**

- 1. DS534, FIR Compiler v5.0 Data Sheet
- 2. XAPP1018, Designing Efficient Wireless Digital Up and Down Converters Leveraging CORE Generator and System Generator
- 3. XAPP1113, Designing Efficient Digital Up and Down Converters for Narrowband Systems
- 4. XAPP1123, 3GPP LTE Digital Front End Reference Design
- 5. 3GPP TS 36.104, 3rd Generation Partnership Project; Technical Specification Group Radio Access Network; Evolved Universal Terrestrial Radio Access (E-UTRA); Base Station (BS) radio transmission and reception; (Release 9)
- 6. 3GPP TR 25.105, 3rd Generation Partnership Project; Technical Specification Group Radio Access Network; Base Station (BS) radio transmission and reception (TDD) (Release 9)
- 7. 3GPP TR 25.104, 3rd Generation Partnership Project; Technical Specification Group Radio Access Network; Base Station (BS) radio transmission and reception (FDD) (Release 9)
- <span id="page-36-0"></span>8. ARM IHI0024B, AMBA 3 APB Protocol, v1.0

# **Support**

Xilinx provides technical support at [www.xilinx.com/support](www.xilinx.com/support/) for this LogiCORE product when used as described in the product documentation. Xilinx cannot guarantee timing, functionality, or support of product if implemented in devices that are not defined in the documentation, if customized beyond that allowed in the product documentation, or if changes are made to any section of the design labeled *DO NOT MODIFY*.

See the *IP Release Notes Guide* ([XTP025\)](www.xilinx.com/support/documentation/ip_documentation/xtp025.pdf) for further information on this core. There is a link to all the DSP IP and then to the relevant core.

For each core, there is a master Answer Record that contains the Release Notes and Known Issues list for the core being used. The following information is listed for each version of the core:

- New Features
- Bug Fixes
- Known Issues

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This LogiCORE IP module is included at no additional cost with the Xilinx Vivado Design Suite and ISE Design Suite and is provided under the terms of the [Xilinx End User License Agreement](http://www.xilinx.com/ise/license/license_agreement.htm). Information about this and other Xilinx LogiCORE IP modules is available at th[e Xilinx Intellectual Property](http://www.xilinx.com/products/intellectual-property/index.htm) page. For information about pricing and availability of other Xilinx LogiCORE IP modules and tools, contact your [local Xilinx sales representative.](http://www.xilinx.com/company/contact/index.htm)

# **Revision History**



The following table shows the revision history for this document:

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